An Efficient Security Access System for Computers using Image Processing Techniques
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Abstract—This paper describes the method for an efficient face recognition system for access control to a computing device while utilizing image processing techniques. This unique method can be used for Windows, Linux, Unix operating systems. The proposed system detects the user’s face with a 98% probability and detects the intruder’s face with less than 1% probability. The detection time for the face is less than 2 seconds and unlocks the system within 2 seconds because of triggering all the tasks from windows, but still making it efficient from the previous works made. Additionally, the system application alerts the user when an intruder tries to unlock the system and also sends the image of the intruder’s face to the user, thus assuring maximum security to the system.

I. INTRODUCTION
Recently, there has been significant interest in the development of facial recognition due to its use in biometric technology which provides good security to any access. This has been very reliable since this method uses distinguished facial features to identify a person hence offering a quick, automatic, seamless verification experience.

<table>
<thead>
<tr>
<th>Graphics Card</th>
<th>Training and Testing Time</th>
<th>RAM</th>
<th>Detection + Unlocking Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 GB**</td>
<td>40 sec</td>
<td>4 GB**</td>
<td>9+9</td>
</tr>
<tr>
<td>6 GB*</td>
<td>20 sec</td>
<td>8 GB*</td>
<td>4+4</td>
</tr>
<tr>
<td>12 GB*</td>
<td>10 sec</td>
<td>16 GB*</td>
<td>2+2</td>
</tr>
</tbody>
</table>

Table 1. Different System Requirements and their results
Legend: ‘*’ are experimentally verified, ‘**’ are theoretically analyzed

In this paper, a deep neural network model is used to train and test the data. This system is created after studying various deep-learning models and other techniques for image segmentation and enhancement and analyzing their results against our model. This article purely describes only one efficient model and their results have been discussed. Also, this is integrated into the windows and Ubuntu operating system for ubiquity. The proposed system works well for Windows OS 8 and above, Ubuntu version 16 and above.

II. PROCESS
A. Input
A large number of face samples are captured using a haar cascade frontal face algorithm. In this case, 300 images are captured to cover all the possible facial features.

B. Image Segmentation
Firstly, it creates a boundary around the face to be detected using an object detection method. Instance segmentation is done to identify a single instance of the image, in our case a single face. Threshold segmentation sets a threshold value for the pixel values in the picture above which will be discarded for identifying the profile of a face. Mask R-CNN method is applied only for multiple objects so that it masks the background faces and captures only the frontal face [1].

C. Image Enhancement
The first stage in enhancing the image is to convert the RGB image to grayscale for conducting operations on it easily. Due to this conversion step, the background and the face may be blended or distorted, so it is necessary to do a face shape check. After this noise is removed from the image, sharpened and brightened.
D. Face Normalization

Face detection is a process of localizing and extracting the face region from the background. Those features are independent of face features and will affect the recognition rate significantly. The system of feature detection has detected three features such as left eyeball center, right eyeball center & mouth center. Each feature is detected using the Region of Interests (ROI) [2]. Then, Geometric normalization is applied to align the eyeball center and mouth center alignment. Lastly, brightness normalization is done by mean centering the pixel values and linearly smoothening the edges and normalizing the contrast with histogram equalization.

E. Feature Extraction

Feature extraction is the process by which certain features of interest within an image are detected and represented for further processing. Facial landmarks are used to localize and represent salient regions of the face detecting facial landmarks is a subset of the shape prediction problem.

![Fig 2. 68 Point facial landmark vector points](image)

The pre-trained facial landmark detector inside the dlib library is used to estimate the location 68(x,y) coordinates that map to the facial structures on the face [3]. Finally, 9/10th of the data is sent for training. 1/10th of the data is used for testing the data.

F. Feature Classification

Feature mapping is a pattern recognition technique used to categorize a huge number of data into a number of different classes. Firstly, the data is sent into the tensor flow and then into Keras which acts as a top layer to the system [4].

<table>
<thead>
<tr>
<th>No. of Epochs</th>
<th>Batch Size</th>
<th>Learning Rate</th>
<th>Loss</th>
<th>Accuracy</th>
<th>MLP Error</th>
<th>Probability</th>
</tr>
</thead>
<tbody>
<tr>
<td>300</td>
<td>50</td>
<td>0.01</td>
<td>0.16</td>
<td>0.936</td>
<td>4.95%</td>
<td>98.2%</td>
</tr>
<tr>
<td>500</td>
<td>30</td>
<td>0.1</td>
<td>0.01</td>
<td>0.998</td>
<td>14.5%</td>
<td>64.8%</td>
</tr>
<tr>
<td>150</td>
<td>50</td>
<td>0.01</td>
<td>0.38</td>
<td>0.62</td>
<td>8.23%</td>
<td>88.4%</td>
</tr>
</tbody>
</table>

Table 2. Results by changing different parameters.

III. CONCLUSIONS

An efficient system for face recognition is created after studying various methods and analyzing them to increase the robustness and accuracy of the system. It is also integrated into the windows operating system without compromising the OS-user agreement by triggering tasks in the Windows task manager. Therefore, the system is very reliable and accurate with the results shown above. In the future, by increasing the number of facial points one can increase the accuracy of the system as more vector coordinates give many efficient results.

IV. ACKNOWLEDGMENTS

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VI. REFERENCES